

3.1

3.2

3. 3

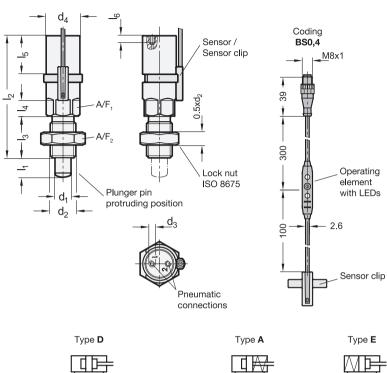
3.4

3.5

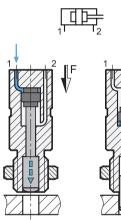
3.6

3.7

0.0 0.0

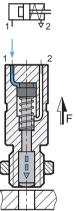


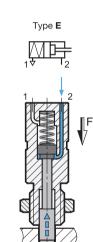
M	ətric
9	
00	Stainless TO-Link
4 D	Pneumatically double-acting,
А	protrude / retract Pneumatically single-acting,
E	retract by spring force Pneumatically single-acting, protrude by spring force
5	Coding
OP BS0,4	Without position query Position query on both sides, with plug, cable 0.4 m



Retracted position Pre

Protruding position





Q	2	3	Dimensions in: millimeters - inches									
d₁ Pin ^{-0.02} Bore H7	I ₁	d ₂	d ₃	d ₄	l ₂	I ₃	I ₄	I ₅	l ₆ min.	A/F ₁	A/F ₂	
6 0.236	9 <i>0.35</i>	M 12 x 1.5	M 3	21 <i>0.83</i>	73 <i>2.</i> 87	22 0.87	10 <i>0.3</i> 9	24 0.94	4 0.16	19 <i>0.75</i>	18 <i>0.71</i>	
8 0.315	12 <i>0.47</i>	M 16 x 1.5	M 3	21 <i>0.83</i>	76 <i>2.</i> 99	26 1.02	10 <i>0.39</i>	24 0.94	4 0.16	19 0.75	24 0.94	
10 <i>0.394</i>	12 0.47	M 16 x 1.5	M 3	21 <i>0.83</i>	76 <i>2.</i> 99	26 1.02	10 0.39	24 0.94	4 0.16	19 0.75	24 0.94	
12 0.472	15 <i>0.59</i>	M 20 x 1.5	M 3	21 <i>0.83</i>	76 2.99	34 <i>1.34</i>	10 0.39	24 0.94	4 0.16	19 0.75	30 1.18	

Type D Force F at 6 bar ≈		Type A Spring force F ≈		Type E Spring force F ≈			
When protruding	When retracting	Retracted	Protruding	Retracted	Protruding		
65 N	50 N	12 N	26 N	26 N	12 N		
14.61 lbf	11.24 lbf	2.70 lbf	5.85 lbf	5.85 lbf	2.70 lbf		

3.10

GN 817.7 Indexing Plungers continued (2/3)



Specification

- Body
- Stainless steel AISI 303
- Plunger pin surface hardened
- Rod seal
- Polyurethane (PUR)
- Piston seal and O-ring Acrylonitrile butadiene rubber (NBR)
- Magnet
- Neodymium, iron, boron (NdFeB)
- Sensor
- Housing
- Polyamide (PA), black
- Cable and plug
- Outer sheath polyurethane (PUR), black
 Sensor clip
- Polyacetal (POM), black
- Hex nut ISO 8675

Stainless steel AISI 304

• IP Protection Classes → page QVX

ISO Fundamental Tolerances → page QVX

- Plastic Characteristics → page QVX
- Stainless Steel Characteristics → page QVX
- RoHS compliant

Accessory

• Cable with connector coupling GN 330 → page QVX

Information

Indexing plungers GN 817.7 with pneumatic operation can be easily and securely integrated into automated processes and can be positioned at locations where hand operation of the indexing plunger is not possible. Thanks to the material used, the indexing plungers are also suitable for more aggressive environments.

An integrated magnet allows the plunger pin position to be queried electronically by a sensor. The end limits (protruding and retracted position) are taught-in via the operating element on the sensor cable. They each send a high signal, which is indicated by the respective LED and can be processed by a machine control, for example.

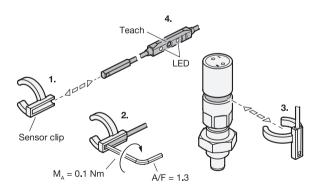
The sensor electronics can also be accessed via IO-Link and offer the ability to set and read out the switching points and to block the teach button on the operating element. To avoid interference, no external magnetic fields should act on the indexing plunger. The pneumatic indexing plungers are supplied with a lock nut. With coding BS0,4, the sensor, sensor clip and an allen wrench are also supplied loose.

see also ...

- List of Indexing Plunger Types → page QVX
- Indexing Plungers GN 717 (with Pull Ring / with Wire Loop) → page QVX
- Indexing Plungers GN 722.4 /.5 /.6 (with Pull Ring) → page QVX / QVX / QVX
- Indexing Plungers GN 817 → page QVX
- Indexing Plungers GN 817.6 (with Sensor for Position Monitoring) → page QVX

How to order	1	Pin diameter d ₁
€ € € € GN 817.7-10-12-M16X1.5-D-BS0.4	2	Stroke I ₁
	3	Thread d ₂
	4	Туре
	5	Coding

Assembly instructions



The radial position of the sensor cable can be freely determined when installing the sensor clip.

Installation steps:

- 1. Insert the sensor into the sensor clip from the side.
- 2. Tighten the hexagon socket screw of the sensor.
- 3. Clip the sensor clip into the ring groove of the indexing plunger and then adjust the position by turning, if necessary.
- 4. During commissioning, teach the sensor to the end positions via the operating element or IO-Link in accordance with the operating instructions supplied with the sensor.

GN 817.7 Indexing Plungers continued (3/3)



		3.1
Pneumatic properties		
Operating pressure	4 - 6 bar	
Operating medium	Filtered, dried air, unoiled or oiled	
Temperature range	-4 °F +176 °F (-20 °C +80 °C)	3.2

Electrical properties of the sensor							
Output function	2x normally open (NO)	 - 1 L+					
Output type	2x PNP	→ = 2 Q1	3 3 3				
Supply voltage	12 - 30 V DC						
Continuous current I _a	≤ 100 mA	——————————————————————————————————————					
Connection type Plug (S)	4-pole connector M8x1, freely rotating with knurled screw connection		3.4				
Protection type	IP 67						
Power consumption	≤ 15 mA		3.5				
Voltage drop	≤ 2.2 V	≤ 2.2 V					
Protection class	111	III					
Temperature range	-4 °F +167 °F (-20 °C +75 °C)						
Shock and vibration resistance	30 g, 11 ms / 10 55 Hz, 1 mm						
EMV	According to EN 60947-5-2						
Reverse polarity protection	Yes						
Short-circuit protection	Yes						
Activation impulse suppression	Yes		3.7				
Communication interface	IO-Link (V1.0) Cycle time 2.3 ms Process data length 2 bits Process data structure: Bit $0 =$ Switching signal Q_1 Bit $1 =$ Switching signal Q_2 Bit 27 = Empty		0				
Approvals, conformity declarations	CE	O IO-Link	6				

3.10

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